

Lattice-based linear solver and number field computations

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Solving linear systems

Original problem

Given an invertible sparse \mathbf{A} of dimension n over the Euclidean ring \mathcal{R} , solve $\mathbf{A}x = y$ over the fraction field. The coordinates of x are fractions with denominator $\det \mathbf{A}$.

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New problem

Given an invertible sparse \mathbf{A} over the Euclidean ring \mathcal{R} , solve over \mathcal{R} the equation $\mathbf{A}x + \mathbf{B}y = z \in \mathcal{R}^n$. The random matrix \mathbf{B} has $m \approx \sqrt{n}$ columns; coordinates of x, y have \sqrt{n} bits.

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Objective

Find the class group of $\mathbb{Q}[\sqrt{\Delta}]$ in time:

$$\exp \left((1 + o(1)) \sqrt{\ln(|\Delta|) \ln \ln |\Delta|} \right).$$

Summary

The overall method is to solve $\mathbf{A}\mathbf{x} = \mathbf{y}$ with high precision and then recover the exact solution.

- Ursic-Patarra '76: solve $\mathbf{x} = \mathbf{A}^{-1}\mathbf{y}$ over reals, use continued fractions on each coordinate

$$\begin{pmatrix} 3 & 14 \\ 15 & 92 \end{pmatrix}^{-1} \cdot \begin{pmatrix} 65 \\ 35 \end{pmatrix} \approx \begin{pmatrix} 83.1818 \\ -13.1818 \end{pmatrix} \Rightarrow \mathbf{x} = \begin{pmatrix} 83 + 2/11 \\ -13 - 2/11 \end{pmatrix}$$

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$$\mathbf{A}^{-1} = \begin{pmatrix} 3 & 14 \\ 15 & 92 \end{pmatrix}^{-1} = \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix} \bmod 13$$

$$\begin{pmatrix} 3 & 14 \\ 15 & 92 \end{pmatrix}^{-1} \begin{pmatrix} 65 \\ 35 \end{pmatrix} = \begin{pmatrix} 4 + 12 \cdot 13 + 9 \cdot 13^2 + 4 \cdot 13^3 \\ 1 + 6 \cdot 13 + 3 \cdot 13^2 + 8 \cdot 13^3 \end{pmatrix} \bmod 13^4$$

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- Storjohann '00: solve n systems in parallel, $\tilde{O}(n^\omega)$

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2. Lattice-based linear solver
3. Global field computation

Old iterative algorithms

Sparse matrix

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Iterative refinement (Hensel, Wilkinson, ...)

If we can find \mathbf{x}' such that $\mathbf{A}\mathbf{x}' \approx \mathbf{y}$, the solution is $\mathbf{x} = \mathbf{x}' + \mathbf{A}^{-1}(\mathbf{y} - \mathbf{A}\mathbf{x}')$.

$$\begin{pmatrix} 3 & 14 \\ 15 & 92 \end{pmatrix} \cdot \begin{pmatrix} 83 \\ -13 \end{pmatrix} = \begin{pmatrix} 65 \\ 35 \end{pmatrix} + \begin{pmatrix} 2 \\ 14 \end{pmatrix}$$
$$\begin{pmatrix} 3 & 14 \\ 15 & 92 \end{pmatrix} \cdot \begin{pmatrix} 18 \\ -18 \end{pmatrix} = \begin{pmatrix} -200 \\ -1400 \end{pmatrix} + \begin{pmatrix} 2 \\ 14 \end{pmatrix}$$

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Jacobi's solver

If $\mathbf{A} \approx \mathbf{D}$, select $\mathbf{x}' = \mathbf{D}^{-1}\mathbf{y}$. If $\forall i, |\mathbf{A}_{i,i}| \geq K \sum_{j \neq i} |\mathbf{A}_{i,j}|$, the error is divided by K .

Conjugate gradient

Conjugate gradient, Lanczos 50s

For $\mathbf{G} > 0$ (positive symmetric definite), let $\kappa = \frac{\lambda_{\max}}{\lambda_{\min}}$; we fix $\lambda_{\min} = 1$.

Accelerated gradient descent/Conjugate gradient: $\sqrt{\kappa} \log(\epsilon^{-1})$ matrix-vector products.

Proof: appendix.

Our algorithm, Cholesky decomposition step

Norm equation

If we have $\mathbf{A}^t \mathbf{A} \mathbf{x} = \mathbf{A}^t \mathbf{y}$ then $\mathbf{A} \mathbf{x} = \mathbf{y}$. Split the matrix \mathbf{A} vertically into two matrices $(\mathbf{E} \quad \mathbf{F})$ with \mathbf{F} having $K \ll n$ columns.

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LDL decomposition of $\mathbf{A}^t \mathbf{A}$

With $\mathbf{D}_0 = \mathbf{E}^t \mathbf{E}$, the Schur complement $\mathbf{D}_1 = \mathbf{F}^t \mathbf{F} - (\mathbf{F}^t \mathbf{E}) \mathbf{D}_0^{-1} (\mathbf{F}^t \mathbf{E})^t$ and $\mathbf{L} = \mathbf{F}^t \mathbf{E} \mathbf{D}_0^{-1}$ of dimension $K \times (n - K)$, the block LDL decomposition of $\mathbf{A}^t \mathbf{A}$ is

$$\mathbf{A}^t \mathbf{A} = \begin{pmatrix} \mathbf{Id}_{n-K} & 0 \\ \mathbf{L} & \mathbf{Id}_K \end{pmatrix} \begin{pmatrix} \mathbf{D}_0 & 0 \\ 0 & \mathbf{D}_1 \end{pmatrix} \begin{pmatrix} \mathbf{Id}_{n-K} & \mathbf{L}^t \\ 0 & \mathbf{Id}_K \end{pmatrix}$$

with \mathbf{D}_1 a $K \times K$ matrix.

Cholesky decomposition

With $\mathbf{L} = \mathbf{F}^t \mathbf{E} \mathbf{D}_0^{-1}$:

Inverse

$$(\mathbf{A}^t \mathbf{A})^{-1} = \begin{pmatrix} \mathbf{Id}_{n-K} & -\mathbf{L}^t \\ 0 & \mathbf{Id}_K \end{pmatrix} \begin{pmatrix} \mathbf{D}_0^{-1} & 0 \\ 0 & \mathbf{D}_1^{-1} \end{pmatrix} \begin{pmatrix} \mathbf{Id}_{n-K} & 0 \\ -\mathbf{L} & \mathbf{Id}_K \end{pmatrix}.$$

Two multiplications by \mathbf{D}_0^{-1} , one by \mathbf{D}_1^{-1} , plus negligible (\mathbf{E}, \mathbf{F} sparse).

Our fast random matrix solver

Conditioning

We solve by $\mathbf{D}_0 = \mathbf{E}^t \mathbf{E}$ using the conjugate gradient. It is believed that $\kappa \approx \frac{n^2}{K^2}$, since \mathbf{E} is sparse, the complexity is $\tilde{O}(\sqrt{\kappa} \cdot n) = \tilde{O}(n^2/K)$.

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Precomputation step of our algorithm

Precompute the dense $K \times K$ matrix $\mathbf{D}_1 = \mathbf{F}^t \mathbf{F} - (\mathbf{F}^t \mathbf{E}) \mathbf{D}_0^{-1} (\mathbf{F}^t \mathbf{E})^t$ with K calls to \mathbf{D}_0^{-1} for a cost of $\tilde{O}(K \cdot n^2/K) = \tilde{O}(n^2)$. Precompute the inverse \mathbf{D}_1^{-1} , with complexity $\tilde{O}(K^\omega)$.

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\mathbf{D}_1^{-1}

Use standard multiplication for \mathbf{D}_1^{-1} , with complexity $O(K^2)$.
It is faster for numerous vectors at the same time, $\mathbf{A}\mathbf{X} = \mathbf{Y}$.

Our results

Diagonally-dominant case

If \mathbf{A} is a diagonally-dominant matrix, we have $\tilde{O}(n)$ per system and bit.

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$$\omega = 3$$

Take $K = n^{2/3}$ and after a precomputation of complexity $\tilde{O}(n^2)$ we have a complexity in $\tilde{O}(n^2/K + K^2) = \tilde{O}(n^{4/3})$ per system and bit.

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Full inverse

We want to solve n linear systems with \sqrt{n} bits.

Use Storjohann's high-order lifting: we solve $n^{1.3}$ systems with precision $n^{0.2}$ bits.

Take $K = n^{0.87}$, use fast rectangular matrix multiplication, and we obtain $n^{1.13}$ per system and bit.

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Problem

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Since $x \in \mathcal{R}^n$ and $y \in \mathcal{R}^m$, this is a lattice problem of dimension $n + m$.

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Projection

We sample a matrix \mathbf{P}^t in \mathcal{R} , and solve instead $\mathbf{P}^t\mathbf{A}x + \mathbf{P}^t\mathbf{B}y = \mathbf{P}^tz$, or $x' + \mathbf{P}^t\mathbf{A}^{-1}\mathbf{B}y = \mathbf{P}^t\mathbf{A}^{-1}z$.

With m columns, we now have a lattice of dimension $2m \approx 2\sqrt{n}$.

Precomputation

Our algorithm, precomputation of NTRU lattice

We compute $\tilde{\mathbf{C}} \approx \mathbf{C} = \mathbf{P}^t \mathbf{A}^{-1} \mathbf{B}$. Then with $\epsilon = \|\tilde{\mathbf{C}} - \mathbf{C}\|$ we reduce the lattice

$$\begin{pmatrix} \mathbf{Id}_m & \tilde{\mathbf{C}} \\ 0 & \epsilon \mathbf{Id}_m \end{pmatrix} \mathcal{R}^{2m}.$$

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Property

Suppose the columns of \mathbf{B} generate $\mathcal{R}^n / \mathbf{A} \mathcal{R}^n$. Then the lattice of $x + \mathbf{A}^{-1} \mathbf{B} y = 0$ has volume $\text{vol}(\mathbf{A}) = |\det \mathbf{A}|$.

We expect to find the sublattice of all y in the NTRU lattice:

$$\begin{pmatrix} (\tilde{\mathbf{C}} - \mathbf{C})y \\ \epsilon y \end{pmatrix}.$$

Proof next slide.

Proof of precomputation success

Assumptions

Linear combinations $\mathbf{B}y$ cover $\mathcal{R}^n / \mathbf{A}\mathcal{R}^n$ with $\|y\| \leq M$; same for \mathbf{P} and \mathbf{A}^t .

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Proof of assumption by the Gaussian technique, from Hildebrand

Only if the rank of $\mathcal{R}^n/\mathbf{A}\mathcal{R}^n$ is less than $m - 2$.

Sample y according to a discrete Gaussian with standard deviation

$\approx \text{vol}(\mathbf{A})^{1/m} \leq \|\mathbf{A}\|^{n/m}$. Then if $\mathbf{B} \bmod \mathbf{A}$ is sampled uniformly, $\mathbf{B}y$ is uniform modulo \mathbf{A} .

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Lattice property

Let $\|\epsilon y\|, \|x' + \mathbf{C}y\| \leq 1/(3nM\|\mathbf{A}\|)$. Consider $\mathbf{P}z = e_i + \mathbf{A}^t w$, $\|z\| \leq M$.

Then $(\mathbf{A}^{-1}\mathbf{B}y)_i = e_i^t \mathbf{A}^{-1}\mathbf{B}y = (z^t \mathbf{P}^t - w^t \mathbf{A})\mathbf{A}^{-1}\mathbf{B}y$ which is

$$z^t \mathbf{C}y - w^t \mathbf{B}y = z^t(x' + \mathbf{C}y) \bmod 1$$

but $\mathbf{B}y = \mathbf{A}(\mathbf{A}^{-1}\mathbf{B}y) \in \mathcal{R}^n$ so $\mathbf{A}^{-1}\mathbf{B}y \in \mathcal{R}^n$.

Our fast solver

Precomputation complexity

We have m systems to be solved with precision $\|\mathbf{A}\|^{-n/m}$. If \mathbf{A} is diagonally-dominant this takes $\tilde{O}(n^2)$.

Reducing a dimension $2m$ lattice with precision n/m takes time $\tilde{O}(m^\omega \cdot n/m)$.

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Extracting a solution

Suppose there is a solution $\mathbf{A}\mathbf{x} + \mathbf{B}\mathbf{y} = \mathbf{z}$. This leads to a solution of the form $\mathbf{x}' + \mathbf{C}\mathbf{y} = \mathbf{P}^t \mathbf{A}^{-1} \mathbf{z}$, given by a lattice point close to

$$\begin{pmatrix} \mathbf{P}^t \mathbf{A}^{-1} \mathbf{z} \\ 0 \end{pmatrix} \approx \begin{pmatrix} \mathbf{x}' + \tilde{\mathbf{C}}\mathbf{y} \\ \epsilon \mathbf{y} \end{pmatrix}.$$

Then $\mathbf{x} = \mathbf{A}^{-1}(\mathbf{z} - \mathbf{B}\mathbf{y})$.

We need to solve a system with precision \sqrt{n} .

Invariant factors

If \mathbf{B} generates $\mathcal{R}^n / \mathbf{A}\mathcal{R}^n$, we obtain the invariant factors from lattice reduction, in particular $|\det \mathbf{A}|$.

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Block Wiedemann (Coppersmith, Villard, Kaltofen)

Take $\mathcal{R} = \mathbb{K}[X]$, for example $\mathbb{K} = \mathbb{F}_q$. For solving $-\mathbf{E}x = y$, choose $\mathbf{A} = X\mathbf{Id}_n - \mathbf{E}$ and reduce modulo X the solution. \mathbf{A} is diagonally-dominant and $\mathbf{A}^{-1} = \sum_{i=0}^{\infty} X^{-i-1} \mathbf{E}^i$. We obtain Eberly *et al.*'s 2007 solver with complexity $\tilde{O}(n^{1.5})$.

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Peng-Vempala, Nie

With $\mathbb{K} = \mathbb{Q}$, $\mathcal{R} = \mathbb{Q}[X]$, \mathbf{B}, \mathbf{P} sampled according to Gaussians, polynomial lattice reduction is well-conditioned. We can compute $\det \mathbf{E}$ within 1.1 in time $O(n^{2.34})$.

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Problems

Consider $\mathbb{K} = \mathbb{Q}[x]/f(x)$ a number field, with $\mathcal{O}_{\mathbb{K}}$ its maximal order of integers.

- Find ideals $\mathfrak{g}_1, \dots, \mathfrak{g}_k$ generating the class group and their order o_k in the class group with $o_1 \mid \dots \mid o_k$ such that the class group is isomorphic to $\prod_{i=1}^k \langle \mathfrak{g}_i \rangle$
- Given a basis of an ideal \mathfrak{a} , find a decomposition of it, which is the class group exponents a_1, \dots, a_k and a generator $g \in \mathbb{K}$ where $\mathfrak{a} = (g) \prod_{i=1}^k \mathfrak{g}_i^{a_i}$
- Find the $r_{\mathbb{R}} + r_{\mathbb{C}} - 1$ generators u_i of \mathcal{O}^{\times} , the unit group

Definition

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- Find the $r_{\mathbb{R}} + r_{\mathbb{C}} - 1$ generators u_i of \mathcal{O}^{\times} , the unit group

We consider a field with small degree.

Cryptanalysis

Decomposition, or finding the group order cryptanalyze various systems (RSA without trusted setup).

Classical algorithm (Minkowski)

We are given \mathfrak{a} (a basis), compute $v \in \mathfrak{a}^{-1}$. Then $v\mathfrak{a} \subset \mathcal{O}_{\mathbb{K}}$ and of index (norm)
 $\approx \sqrt{|\Delta_{\mathbb{K}}|}$.

Ideal reduction

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Smoothness

Call $\mathfrak{p}_i \forall i \leq B$ the ideals of small norm the *factor basis*, the cardinal is

$$B = \exp \left(\left(\frac{1}{2} + o(1) \right) \sqrt{\ln |\Delta_{\mathbb{K}}| \ln \ln |\Delta_{\mathbb{K}}|} \right).$$

A random ideal of norm $\sqrt{|\Delta_{\mathbb{K}}|}$ has probability $1/B$ of factoring over the base.

Generalized Riemann Hypothesis

Prime ideals \mathfrak{p} with norm below $\approx \log^2(|\Delta_{\mathbb{K}}|)$ generate the class group.

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Descent

Given \mathfrak{a} , we want $v\mathfrak{a} = \prod_i \mathfrak{p}_i^{e_i}$.

We sample $e'_i \in \mathbb{Z}$, reduce $\mathfrak{a} \prod_i \mathfrak{p}_i^{e'_i}$ and detect the smoothness of the norm.

Linear algebra

A relation is of the form $v\mathcal{O}_{\mathbb{K}} = \prod_i \mathfrak{p}_i^{e_i}$. Put the exponents in the columns of **A** and **B**, remove the first \log^2 prime ideals. Any $\mathbf{Ax} + \mathbf{By} = 0$ leads to a relation on the generators. A Smith Normal Form algorithm computes the structure of an abelian group from relations.

Improvements

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Generator (PIP)

Assume a descent on \mathfrak{a} leads to $v\mathfrak{a} = \prod_i \mathfrak{p}_i^{z_i}$.
Then we solve $\mathbf{Ax} + \mathbf{By} = \mathbf{z}$.

Descent

A descent on p_i^D guarantees the generation of a diagonally-dominant matrix of relations **A**.

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Special fields

Special fields have for example $\|f\|$ small so that $ax + b$ are much more likely to be smooth. **A** is then not diagonally-dominant.

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- Slightly improved discrete logarithm for hyperelliptic curves in genus $g \geq 3$

Accelerated gradient descent

Proof.

We take $x' = P(\mathbf{G})y$ for $P \in \mathbb{R}[X]$ of degree $d + 1$, the error is $\|y - \mathbf{G}(P(\mathbf{G})y)\| = \|(1 - XP)(\mathbf{G})(y)\|$. Using the spectral theorem, the relative error is $\leq \sum_{\lambda} |(1 - XP)(\lambda)|$. For T a Chebyshev polynomial, i.e. $T = \frac{1}{2}(X - \sqrt{X^2 - 1})^d + \frac{1}{2}(X + \sqrt{X^2 - 1})^d$, we choose

$$1 - XP = \frac{T\left(\frac{\kappa+1-2X}{\kappa-1}\right)}{T\left(\frac{\kappa+1}{\kappa-1}\right)}$$

so that the error made is $\leq T\left(\frac{\kappa+1}{\kappa-1}\right)^{-1} \approx (1 - 1/\sqrt{\kappa})^d$. □